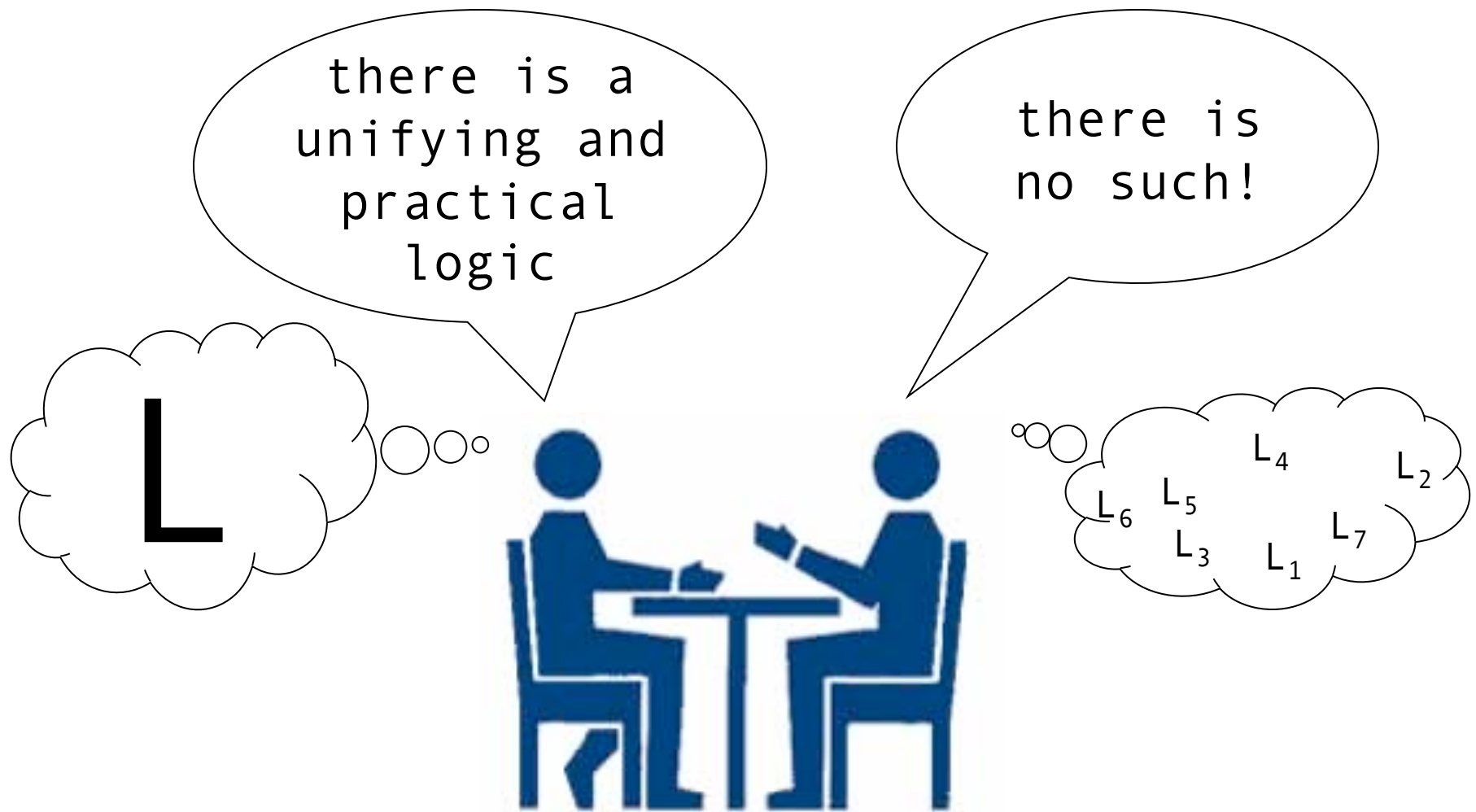

contains material
from RuleR tutorial
written by
Howard Barringer

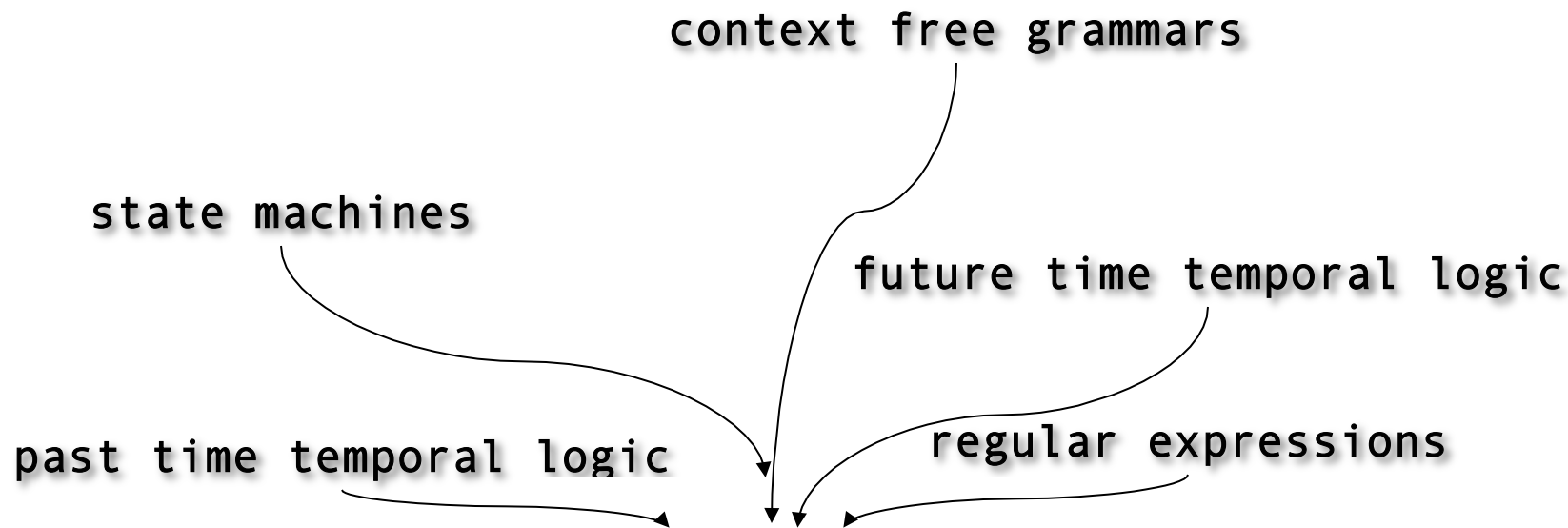
Rule-Based Systems

CS 119

the search for a unifying
monitoring logic



a unifying logic



From Eagle to RuleR

- two attempts to define a super logic:
 - **Eagle** : recursion-based
 - inspired by mu-calculus
 - very convenient logic
 - difficult to implement
 - **RuleR** : rule-based
 - inspired by rule systems from AI and earlier TL work
 - less convenient logic at first sight
 - easy to implement
 - has potential for being basis for convenient logic

Eagle

Howard Barringer
Allen Goldberg
Klaus Havelund
Koushi Sen

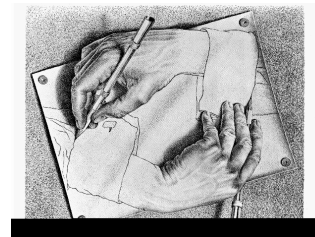


$p \wedge @ q$

temp. logic



functions



recursion

temporality + recursion

- propositional logic + two main temporal connectives:

- **Next:** $@F$

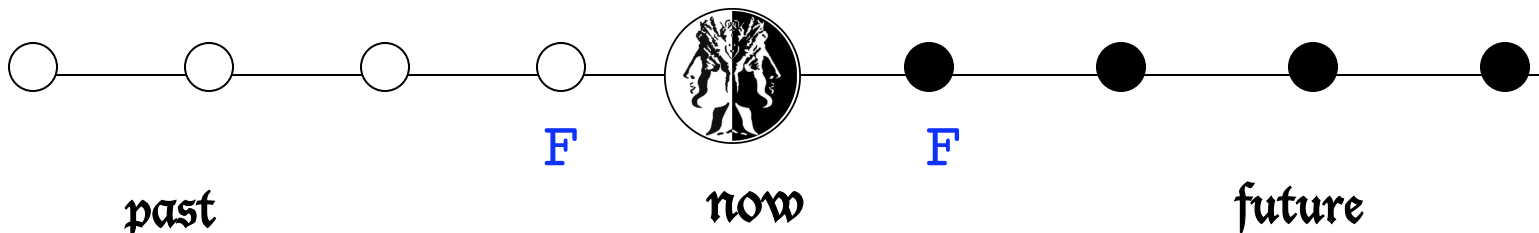
- **Previous:** $\#F$

- **Recursion:**

$\text{safe always}(\text{Term } p) = p \wedge @\text{always}(p)$

$\text{live eventually}(\text{Term } p) = p \vee @\text{eventually}(p)$

$\text{live previously}(\text{Term } p) = p \vee \#\text{previously}(p)$



example:

**Mon M = always(y>0 ->
(previously(x>0) /\ eventually(z>0))) .**

syntax:

$S ::= \mathbf{dec} D \mathbf{obs} O$

$D ::= R^*$

$O ::= M^*$

$R ::= \{ \mathbf{max} \mid \mathbf{min} \} N(T_1 x_1, \dots, T_n x_n) = F$

$M ::= N = F$

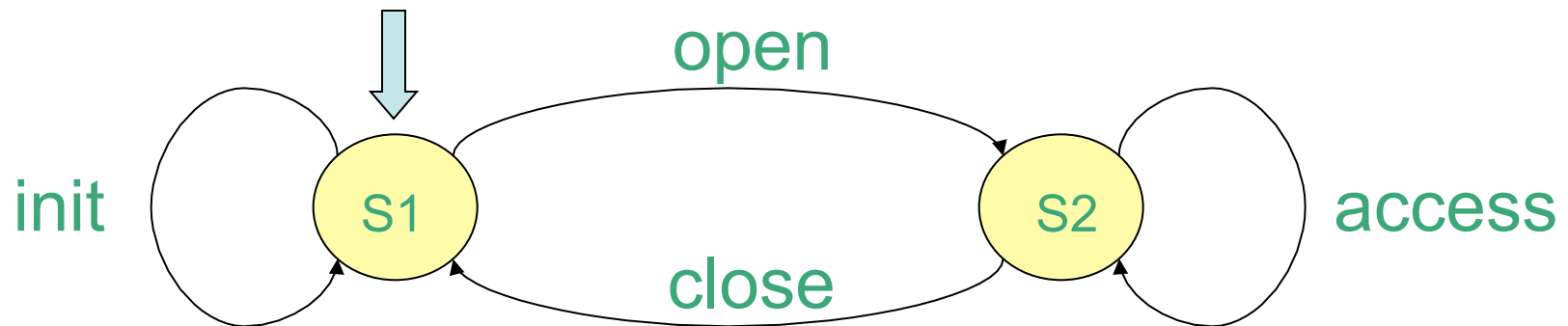
$T ::= \mathbf{Form} \mid \textit{java primitive type}$

$F ::= \textit{java expression} \mid \mathbf{True} \mid \mathbf{False} \mid \neg F \mid F_1 \wedge F_2 \mid F_1 \vee F_2 \mid F_1 \rightarrow F_2 \mid$
 $\bigcirc F \mid \odot F \mid F_1 \cdot F_2 \mid N(F_1, \dots, F_n)$

semantics

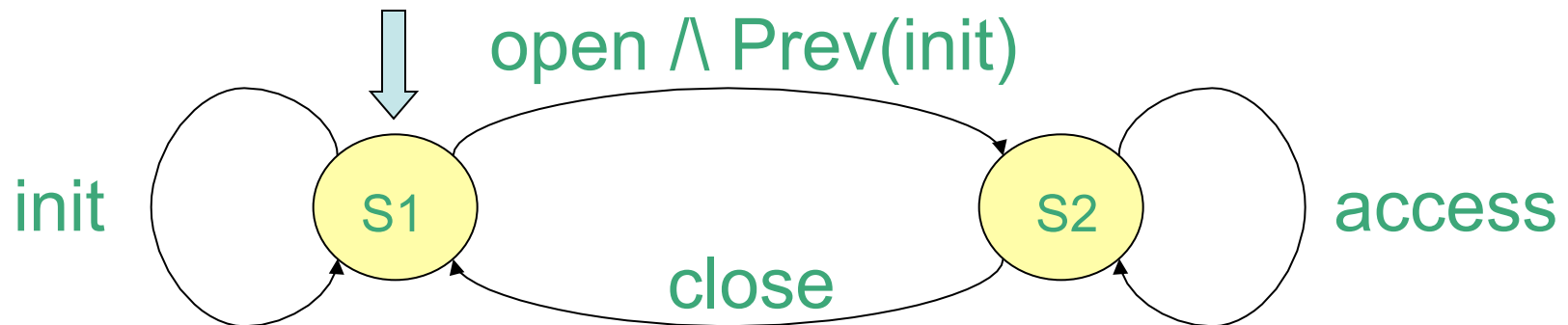
$\sigma, l \models_D \text{exp}$	iff $1 \leq l \leq \sigma $ and $\text{evaluate}(\text{exp})(\sigma(l)) == \text{true}$
$\sigma, l \models_D \text{true}$	
$\sigma, l \not\models_D \text{false}$	
$\sigma, l \models_D \neg F$	iff $\sigma, l \not\models_D F$
$\sigma, l \models_D F_1 \wedge F_2$	iff $\sigma, l \models_D F_1$ and $\sigma, l \models_D F_2$
$\sigma, l \models_D F_1 \vee F_2$	iff $\sigma, l \models_D F_1$ or $\sigma, l \models_D F_2$
$\sigma, l \models_D F_1 \rightarrow F_2$	iff $\sigma, l \models_D F_1$ implies $\sigma, l \models_D F_2$
$\sigma, l \models_D \bigcirc F$	iff $l \leq \sigma $ and $\sigma, l+1 \models_D F$
$\sigma, l \models_D \odot F$	iff $1 \leq l$ and $\sigma, l-1 \models_D F$
$\sigma, l \models_D F_1 \cdot F_2$	iff $\exists j$ s.t. $l \leq j \leq \sigma + 1$ and $\sigma^{(1, j-1)}, l \models_D F_1$ and $\sigma^{[j, \sigma]}, 1 \models_D F_2$
$\sigma, l \models_D N(F_1, \dots, F_m)$	iff $\left\{ \begin{array}{l} \text{if } 1 \leq l \leq \sigma \text{ then:} \\ \quad \sigma, l \models_D F[x_1 \mapsto F_1, \dots, x_{\text{or}} \mapsto F_m] \\ \quad \text{where } (N(T_1 x_1, \dots, T_{\text{or}} x_{\text{or}}) = F) \in D \\ \text{otherwise, if } l = 0 \text{ or } l = \sigma + 1 \text{ then:} \\ \quad \text{rule } N \text{ is defined as } \underline{\text{max}} \text{ in } D \end{array} \right.$

automatae



```
max S1() = init -> @ S1()  
          /\ open -> @ S2()  
          /\ ~(access \/ close) .  
min S2() = access -> @ S2()  
          /\ close -> @ S1()  
          /\ ~(init \/ open) .  
mon M = S1() .
```

combining automata and temporal logic



**max S1() = init -> @ S1()
/\ open /\ Prev(init) -> @ S2()
/\ ~(access \/ close) .**

**min S2() = access -> @ S2()
/\ close -> @ S1()
/\ ~(init \/ open) .**

mon M = S1() .

regular expressions

Property:

File accesses are always enclosed by open and close operations.

$$M = (\text{idle}^*; \text{open}; \text{access}^*; \text{close})^*$$

max $S(\text{Term } t) = t \ / \ \backslash \ @ \ S(t) \ . \ // \ \text{Star}$

min $P(\text{Term } t) = t \ / \ \backslash \ @ \ P(t) \ . \ // \ \text{Plus}$

mon $M =$

$S(S(\text{idle}()); \text{open}()); S(\text{access}()); \text{close}()) \ .$

Property:

Locks are acquired and released nested.

grammars



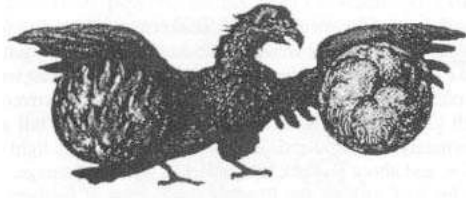
```
lock
release
lock
  lock
  release
release
```

// Match rule:

```
max Match (Term l, Term r) =
  Empty() \ / (l; Match(l, r); r; Match(l, r))
```

// Monitor:

```
mon M = Match(lock(), release())
```

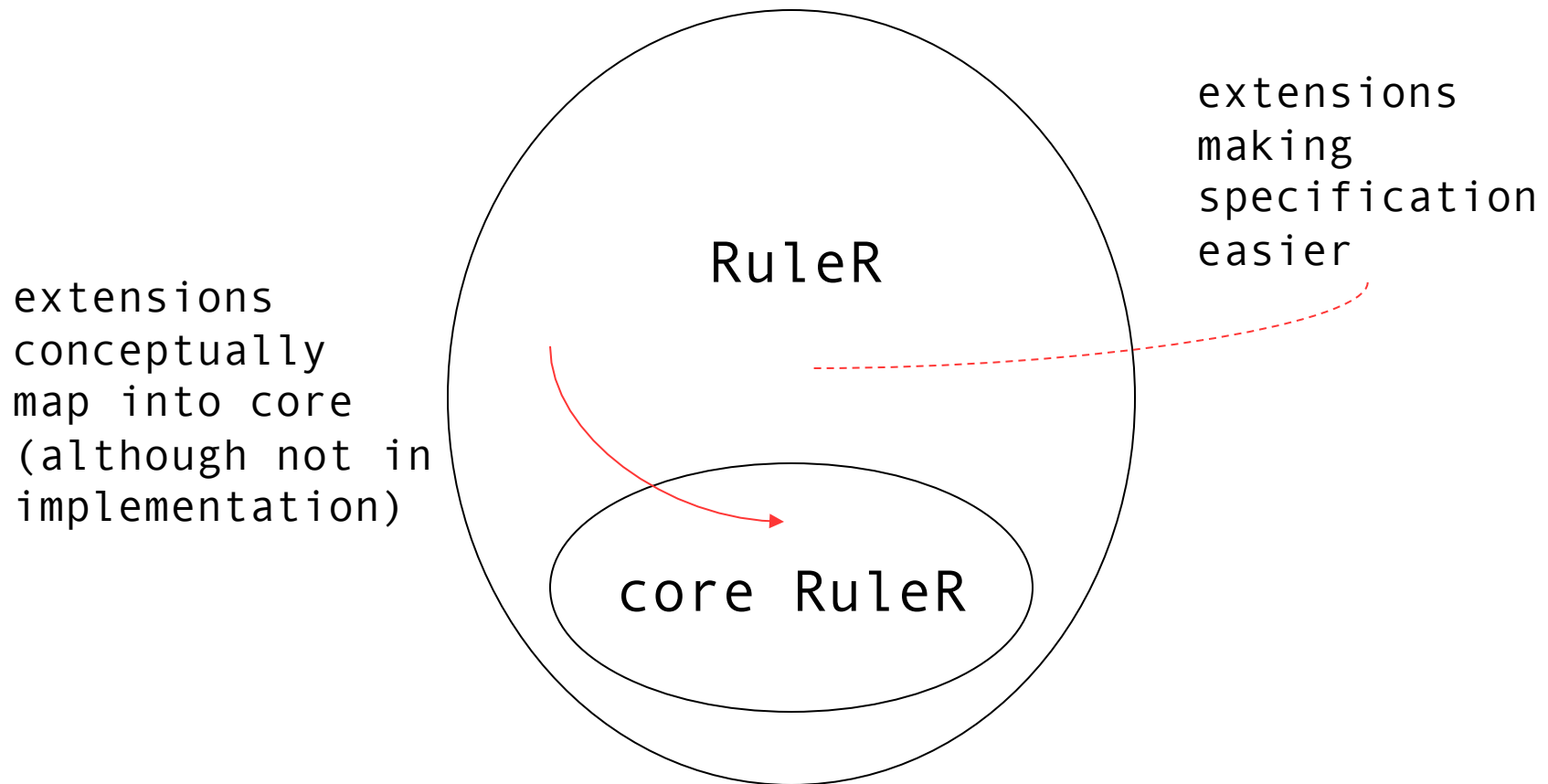


RuleR

Howard Barringer
David Rydeheard
Klaus Havelund

- attempt to develop a core logic for monitoring, a monitoring “byte-code”.
- intended to be simple to implement, and rather low level.
- should support easy mapping from high level logics to RuleR.
- ended up becoming a specification language on its own.

RuleR's core and extensions



the key concept : a rule

If the **lhs** is true in the current State

then the **rhs** is added to the new state (all old information is lost)

R : **lhs** \rightarrow **rhs**

Spec = Rule-set
Rule = State \rightarrow State
State = Fact-set

Example if a is true now b must be true next:

R : a \rightarrow b

RuleR by Example

Examples taken from:

RuleR: A Tutorial Guide
DRAFT: Version 0.1

Howard Barringer

propositional RuleR

Always a

```
ruler Always {  
  ruleIDs { Ra , Rna }  
  observes { a }  
  rules {  
    Ra : a -> Ra , Rna ;  
    Rna : ! a -> Fail ;  
  }  
  initials { Ra , Rna }  
}  
  
monitor {  
  uses { A: Always }  
  run A .  
}
```

□ a

specification monitors 'a' events as well as other events.

rule Ra makes sure rule Rna is continuously activated.

rule Rna (Rule 'not a') emits failure when 'a' is not true.

Eventually a

```
ruler Eventually {  
  ruleIDs { Rb, Rnb }  
  observes { b }  
  rules {  
    Rnb: !b -> Rb, Rnb;  
    Rb: b -> Ok;  
  }  
  initials { Rb, Rnb }  
  forbidden { Rb }  
}  
  
monitor {  
  uses { E: Eventually }  
  run E .  
}
```

rule Rnb makes sure rule Rb is continuously activated.

rule Rb emits built-in Ok signal when 'b' is true.

forbidden rules are not allowed to exist in state at end of monitoring.

◇a

```

ruler RegularPattern {
  ruleIDs { Rg, Rng, Sa, Sb, Sc, Snb, Snac }
  observes { g, a, b, c }
  rules {
    Rg: g -> Sa, Sc, Snac, Rg, Rng;
    Rng: !g -> Rg, Rng;

    Sa: a -> Sb, Snb;
    Sc: c -> Ok;
    Snac: !a, !c -> Fail;

    Sb: b -> Sa, Sc, Snac;
    Snb: !b -> Fail;
  }
  initials { Rg, Rng }
  forbidden { Sa, Sb, Sc }
}

monitor {
  uses { RE: RegularPattern }
  run RE .
}

```

a g should be followed by a sequence of ab's and then a c.

rules Rg and Rng are always active.

in case g occurs, rules Sa, Sc and Snac (not a or c) are activated.

rule Sa and Sb represent the (ab)*-iteration. Sc terminates the (ab)*c loop.

$\square(g \rightarrow (ab)^*c)$

calling RuleR from
AspectJ

the RuleR interface

```
public enum Signal{TRUE,STILL_TRUE,STILL_FALSE,FALSE}
```

```
class RuleR {  
    public RuleR(String fileName , boolean timing ){...}  
  
    public Signal dispatch(String eventName,Object[] argList){...}  
    public Signal dispatch(String eventName){...}  
    public Signal dispatchEnd(){...}
```

```
    ...  
}
```

the RuleR constructor takes fileName prefix and looks for specification in fileName.ruler. Generates output in fileName.output.

two dispatch methods exists, with and without additional event arguments.

emitted
to output
at end:

Signal

- status(0) • **Signal.FALSE:**
 - Property violated, no more monitoring
- status(1) • **Signal.STILL_FALSE:**
 - Property still not satisfied, could be later
- status(2) • **Signal.STILL_TRUE:**
 - Property still not violated, could be late
- status(3) • **Signal.TRUE:**
 - Property satisfied, no more monitoring

an example Java program

```
public class ExampleThree {  
  
    static void a(){...}  
    static void b(){...}  
    static void c(){...}  
    static void g(){...}  
  
    static void end() {...}  
  
    public static void main(String[] args) {  
        a();b();c();  
        g();a();b();a();b();c();  
        a();  
        g();a();c(); ← error  
        b();  
        end();  
    }  
}
```

the aspect calling RuleR

```
package exp;

import rules.RuleR;
import rules.RuleSystem.Signal;

public aspect REPattern {
    RuleR ruler =

        new RuleR("src/examples/REPattern", false);

    pointcut scope() :
        !cflow(adviceexecution()) && if(true);

    pointcut a() : call(void a());
    pointcut b() : call(void b());
    pointcut c() : call(void c());
}
```

no timestamps

specification is in
the file:
`REPattern.ruler`

output is written to
the file:
`REPattern.output`

advice

...

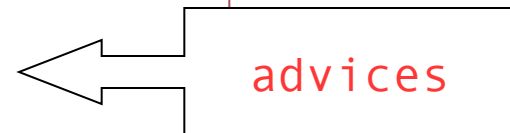
```
before() : a() && scope() {  
    if (ruler.dispatch("a") == Signal.FALSE){  
        System.err.println("Symbol a incorrect");  
        System.exit(0);  
    }  
}
```

```
before() : b() && scope() {...}  
before() : c() && scope() {...}  
before() : g() && scope() {...}
```

```
before() : call(void end()) &&  
    ruler.dispatchEnd();
```

```
}
```

...



reaction must be defined
in aspect code.

aspect code has to emit
end event.

output

Rule system RE.RegularPattern

a called

b called

c called

g called

a called

b called

a called

b called

c called

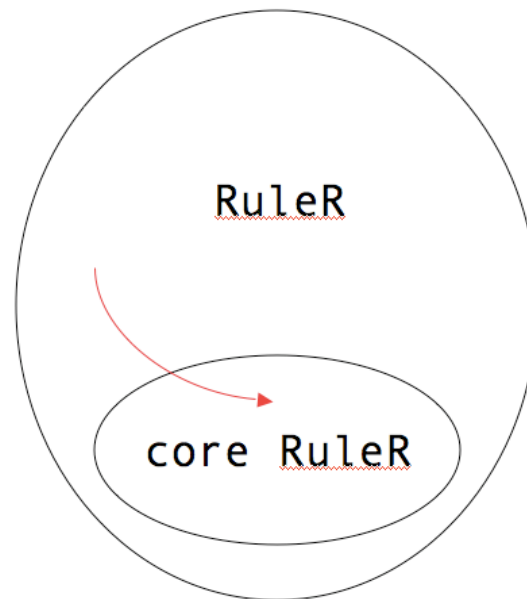
a called

g called

a called

Symbol c incorrect

extending core-RuleR with
three kinds of rule declarations



```

ruler RegularPattern {
  ruleIDs { Rg, Rng, Sa, Sb, Sc, Snb, Snac }
  observes { g, a, b, c }
  rules {
    Rg: g -> Sa, Sc, Snac, Rg, Rng;
    Rng: !g -> Rg, Rng;

    Sa: a -> Sb, Snb;
    Sc: c -> Ok;
    Snac: !a, !c -> Fail;

    Sb: b -> Sa, Sc, Snac;
    Snb: !b -> Fail;
  }
  initials { Rg, Rng }
  forbidden { Sa, Sb, Sc }
}

monitor {
  uses { RE: RegularPattern }
  run RE .
}

```

recall
this
spec

rules in core-RuleR
are "single-shot":

for a rule to persist,
some (perhaps other)
rule must generate
it in each step.

some rules belong
together:

- Sa, Sc and Snac
- Sb, Snb

$\square(g \rightarrow (ab)^*c)$

```

ruler RegularPatternV2 {
  ruleIDs { G, S, T }
  observes { g, a, b, c }
  rules {
    always G {
      g -> S;
    }

    state S {
      a -> T;
      c -> Ok;
      !a, !c -> Fail;
    }

    state T {
      b -> S;
      !b -> Fail;
    }
  }

  initials { G }
  forbidden { S, T }
}

```

reformulation of spec

$\Box(g \rightarrow (ab)^*c)$

three kinds of rules, each with different notion of persistence:

- **always rules**: always active unless explicitly de-activated
- **state rules**: remain active until fired, unless as above
- **step rules**: the basic core semantics, survive one step only, unless re-activated

```

monitor {
  uses {RE : RegularPatternV2}
  run RE .
}

```

rule parameters

```

ruler CountingABC {
  ruleIDs { A, B, C, Terminal }
  observes { a, b, c }
  rules {
    state A(x) {
      a -> A(x+1);
      b -> B(2*x-1, 3*x);
      c -> Fail;
    }
    state B(x, y) {
      x>0, b -> B(x-1, y);
      x=0, c -> C(y-1);
      x!=0, c -> Fail;
      a -> Fail;
    }
    state C(y) {
      y>1, c -> C(y-1);
      y=1, c -> Terminal;
      a -> Fail;
      b -> Fail;
    }
  }
  ...
}

```

monitor this:

$$(a^n b^{2n} c^{3n})^+$$

```

...
state Terminal {
  a -> A(1);
  !a -> Fail;
}
initials { Terminal }
forbidden { A, B, C }
}

```

```

monitor {
  uses {ABC : CountingABC}
  run ABC .
}

```

parameterized events

```

ruler RegularPatternV3 {
  ruleIDs { G, S, T }
  observes { g, a, b, c }
  rules {
    always G {
      g(x) -> S(x);
    }
    state S(x) {
      a, x>0 -> T(x);
      a, x<=0 -> Fail;
      c, x=0 -> Ok;
      c, x!=0 -> Fail;
      !a, !c -> Fail;
    }
    state T(x) {
      b -> S(x-1);
      !b -> Fail;
    }
  }
  initials { G }
  forbidden { S, T }
}

```

monitor this:

$$\forall n \bullet \square(g(n) \rightarrow \bigcirc((ab)^n c))$$

now our aspect must provide 'x' argument to dispatch method whenever 'g' is dispatched.

```

monitor {
  uses {RE : RegularPatternV3}
  run RE .
}

```

```

public aspect REPatternV3 {
    RuleR ruler =
        new RuleR("src/examples/REPatternV3", false);

    pointcut scope() :
        !cfow(adviceexecution()) && if(true);

    pointcut a() : call(void a());
    pointcut b() : call(void b());
    pointcut c() : call(void c());
    ! pointcut g(int x) : call(void g(int)) && args(x);

    before() : a() && scope() {...}
    before() : b() && scope() {...}
    before() : c() && scope() {...}
    ! before(int x) : g(x) && scope() {
    !     if (ruler.dispatch("g", new Object[]{x}) == Signal.FALSE){
        System.err.println("Symbol g incorrect");
        System.exit(0);
    }
    }
    before() : call(void end()) && scope() {...}
}

```

the aspect

conditionals

```

ruler RegularPatternV3 {
  ruleIDs { G, S, T }
  observes { g, a, b, c }
  rules {
    always G {
      g(x) -> S(x);
    }
    state S(x) {
      a, x>0 -> T(x);
      a, x<=0 -> Fail;
      c, x=0 -> Ok;
      c, x!=0 -> Fail;
      !a, !c -> Fail;
    }
    state T(x) {
      b -> S(x-1);
      !b -> Fail;
    }
  }
  initials { G }
  forbidden { S, T }
}

```

back to the spec:

$$\forall n \bullet \square(g(n) \rightarrow \bigcirc((ab)^n c))$$

common terms

arithmetic conditions are
complementary ($x>0, x\leq 0$)

conditionals

```

monitor {
  uses {RE : RegularPatternV3}
  run RE .
}

```

```

ruler RegularPatternV4 {
  ruleIDs { G, S, T }
  observes { g, a, b, c }
  rules {
    always G {
      g(x) -> S(x);
    }

    state S(x) {
      a { : x>0 -> T(x);
          -> Fail;
        : }
      c { : x=0 -> Ok;
          -> Fail;
        : }
      !a, !c -> Fail;
    }

    state T(x) {
      b -> S(x-1);
      !b -> Fail;
    }
  }
}

```

using conditionals

$\forall n \bullet \square(g(n) \rightarrow \bigcirc((ab)^n c))$

← conditional

← conditional

```

initials { G }
forbidden { S, T }
}

```

```

monitor {
  uses {RE: RegularPatternV4}
  run RE .
}

```

parameterized rule schemas

```

ruler Always(Y) {
  ruleIDs { R }
  rules {
    always R(x) {
      x -> Ok;
      !x -> Fail;
    }
  }
  initials {Y,R(Y)}
}

ruler Eventually(Y) {
  ruleIDs { R }
  rules {
    step R(x) {
      x -> Ok;
      !x -> R(x);
    }
  }
  initials {R(Y)}
  forbidden {R}
}

```

monitor this:

$$\Box(g \rightarrow \Box a) \wedge \Box(h \rightarrow \Diamond b)$$

```

ruler Comb {
  uses {A:Always,E:Eventually}
  ruleIDs { R }
  observes {g,h,a,b}
  rules {
    always R {
      g -> A(a);
      h -> E(b);
    }
  }
  initials { R }
}

```

```

monitor {
  uses {C:Comb}
  run C .
}

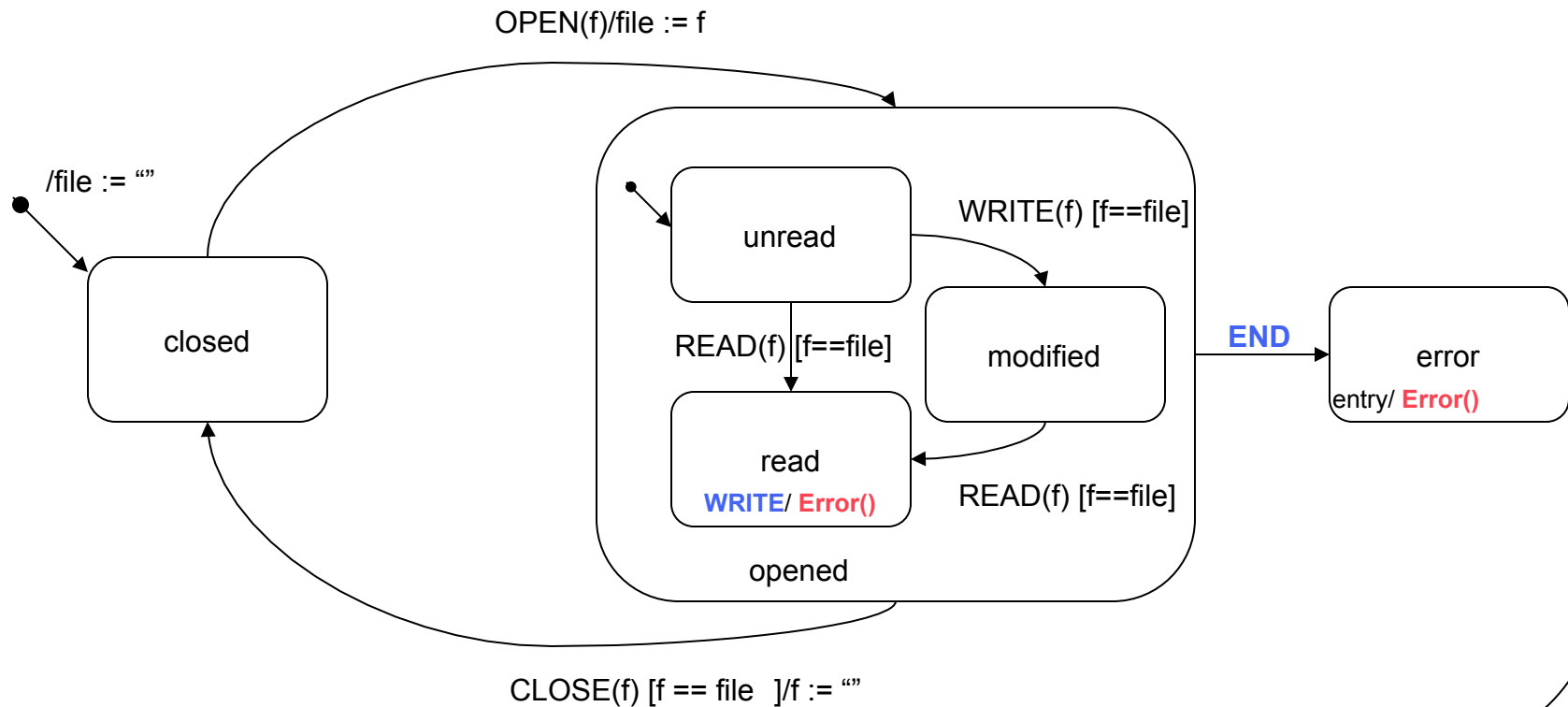
```

super rules

inspired by UML state charts

variables
char *file;

close opened files eventually
and don't write after a read.



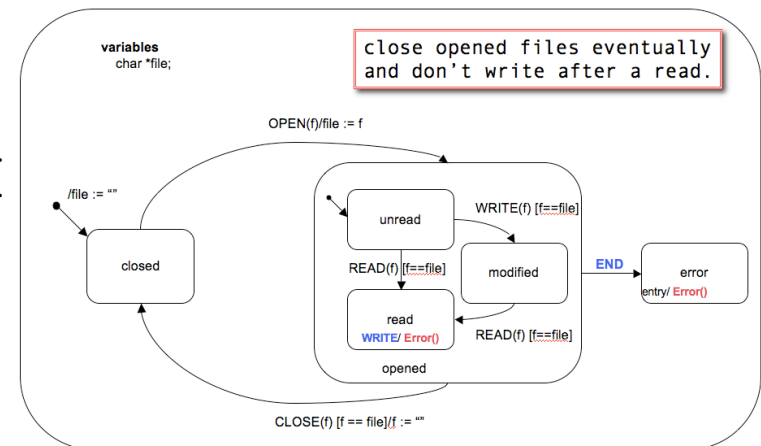
```

ruler FileMonitor {
  ruleIDs {Start,Opened,Unread,Read,Modified}
  observes {OPEN,END,CLOSE,READ,WRITE}
  rules {
    always Start {
      OPEN(f), !Opened(f) -> Unread(f);
    }
    state Opened(f) super {Unread,Read,Modified} {
      END -> Fail;
      CLOSE(f) -> Ok;
    }
    state Unread(f) extends Opened {
      READ(f) -> Read(f);
      WRITE(f) -> Modified(f);
    }
    state Read(f) extends Opened {
      WRITE(f) -> Fail;
    }
    state Modified(f) extends Opened {
      READ(f) -> Read(f);
    }
  }
  initials {Start}
}

```

super
rules

activating a sub-rule
also activates super
rule.



real time and rule piping

requirements

- the **events**: `openDoor`, `passDoor`, `closeDoor`.
- once a door has been opened, it **should be automatically closed** within a certain time, unless something has passed through the door in the intervening period, which resets the timer.
- only a **limited number of doors** may be open at any one time.

```

ruler AlarmedDoorMonitor(maxopen, alarm) {
  ruleIDs { Start, Opened }
  observes { openDoor, closeDoor, passDoor, time }
  rules {
    state Start(x, max) {
      openDoor(door, timelimit), time(t)
      {: x<max -> Opened(door, timelimit, t), Start(x+1, max);
        -> alarm;
      :}
    }
    state Opened(door, timelimit, opentime) {
      time(now)
      {: now-opentime < timelimit
        {: closeDoor(door), Start(x, max)
          -> !Start(x, max), Start(x-1, max);
          passDoor(door) -> Opened(door, timelimit, now);
        :}
        -> alarm;
      :}
    }
  }
}

initials { Start(0, maxopen) }
outputs { alarm }

```

```
ruler AlarmHandler(alarm) {  
  ruleIDs { Start }  
  rules {  
    state Start {  
      alarm -> Fail;  
    }  
  }  
  initials { Start }  
}
```

rule schemas are being
piped together
communicating via the
bell

```
monitor {  
  uses { D: AlarmedDoorMonitor,  
          H: AlarmHandler }  
  locals { bell }  
  run (D(3,bell) >> H(bell)) .  
}
```

```
public static void main (String [] args){
    CheckDoor me = new CheckDoor();

    Door doorA = me.new Door("A"),
        doorB = me.new Door("B"),
        doorC = me.new Door("C"),
        doorD = me.new Door("D");

    for (int n = 10000; n > 0; n=n-3){
        doorA.openDoor(10*n);
        doorB.openDoor(10*(n-1));
        doorC.openDoor(10*(n-2));
        doorC.passDoor();
        doorC.closeDoor();
        doorB.passDoor();
        doorB.closeDoor();
        doorA.closeDoor();
    }

    end();
}
```

an application

turn time-stamping on

```
public aspect AlarmedMonitor {
    RuleR ruler = new RuleR("...", true);

    pointcut openDoor(CheckDoor.Door d, int limit) :
        call(* exp.CheckDoor.Door.openDoor(int)) &&
        target(d) && args(limit);
    pointcut closeDoor(CheckDoor.Door d) :
        call(* exp.CheckDoor.Door.closeDoor()) && target(d);
    pointcut passDoor(CheckDoor.Door d) :
        call(* exp.CheckDoor.Door.passDoor()) && target(d);

    before(CheckDoor.Door d, int limit):
        openDoor(d, limit) && scope()
    {
        Signal s = ruler.dispatch("openDoor", new Object[]{d, limit});
        if (s==Signal.FALSE){...}
    }

    before(CheckDoor.Door d): passDoor(d) && scope(){...}
    before(CheckDoor.Door d): closeDoor(d) && scope(){...}
    after() : call(void end()) && scope() {...}
}
```

the aspect

asserting progress

```

ruler SimpleCFLV2 {
  ruleIDs { S, L, U, E }
  observes { lock, unlock }

  rules {
    step S {
      lock -> L(E);
    }
    step L(c) {
      lock -> L(U(c));
      unlock -> c;
    }
    step U(c) {
      unlock -> c;
    }
    step E {
      -> Fail;
    }
    assert { S, L, U }
  }
  initials { S | E }
  forbidden { S, L, U }
}

```

monitor this:

lockⁿ unlockⁿ

assert {R₁, ..., R_n}

fails if not at least
one of the rules R₁,
..., R_n fire.

```

monitor {
  uses {S: SimpleCFLV2}
  run S .
}

```

```

ruler SimpleCFLV2 {
  ruleIDs { S, L, U, E }
  observes { lock, unlock }

  rules {
    step S {
      lock -> L(E);
    }
    step L(c) {
      lock -> L(U(c));
      unlock -> c;
    }
    step U(c) {
      unlock -> c;
    }
    step E {
      -> Fail;
    }
  }
  assert { S, L, U }
}
initials { S | E }
forbidden { S, L, U }
}

```

monitor this:

lockⁿ unlockⁿ

	S E
lock	L(E)
lock	L(U(E))
lock	L(U(U(E)))
unlock	U(U(E))
unlock	U(E)
unlock	E

```

monitor {
  uses {S: SimpleCFLV2}
  run S .
}

```

advanced rule piping
using parameterized events

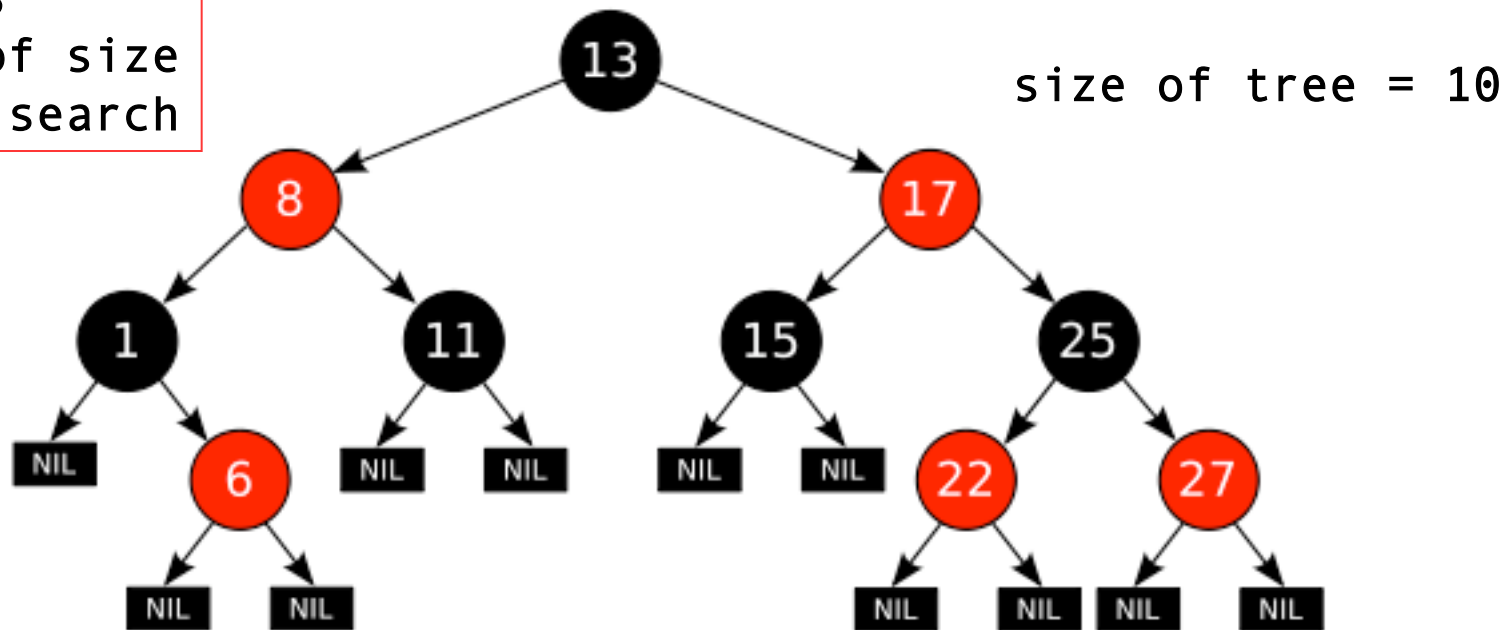
Repeated searches in binary tree

report when there are 1.5 times more bad searches than good searches:

- good search: max search depth $< G\%$ of tree size
- bad search: max search depth $> B\%$ of tree size

find(x)
= 1 if x is in tree
= 0 if x is not in tree

find(6):
depth=3
< 33% of size
= good search



```

ruler Trace {
  ruleIDs { Top, Stack }
  observes { call, return }
  locals { result }
  rules {
    state Top{
      call(tree,size) -> Stack(tree, 1, 1, size);
    }
    state Stack(tree, level, max, size){
      call(x, y) -> Stack(tree, level+1, max+1, size);
      return(x, b)
        {: level=1
          {: b=1 -> result(tree, max, size), Top;
            -> Top;
          :}
          -> Stack(tree, level-1, max, size);
        :}
      }
    }
  }
  initials { Top }
  outputs { result }
}

```

```

ruler Stats(G, B) {
  ruleIDs { Start, Track }
  observes { T.result }
  locals { report }
  rules {
    always Start {
      T.result(t, m, s), !Track(t,x,y)
      {: m*100 < G*s -> Track(t,1,0);
        m*100 > B*s -> Track(t,0,1);
          -> Track(t,0,0);
        :}
    }
    state Track(tree, Gs, Bs){
      T.result(tree, m, s)
      {: m*100 < G*s -> Track(tree, Gs+1, Bs);
        m*100 > B*s -> Track(tree, Gs, Bs+1);
          -> Track(tree, Gs, Bs);
        :}
      (Bs != 0) & (Gs !=0 ) & (2*Bs > 3*Gs) ->
        report(tree, Bs, Gs);
    }
  }
}

```

```

monitor {
  uses {T: Trace,S: Stats}
  run (T >> S(33, 50)) .
}

```

```

initials { Start }
outputs { report }

```

properties of Java library APIs

The screenshot shows the Java API documentation for the `Iterator` interface in the `java.util` package. The page includes navigation tabs, a left sidebar with a package tree, and the main content area. A red box highlights a property R_1 with the text: "There should be no two calls to `next()` without a call to `hasNext()` in between, on the same iterator." The main content area also includes the interface signature, subinterfaces, implementing classes, a description of the interface, and a method summary table.

Overview Package Class Use Tree Deprecated Index Help

PREV CLASS NEXT CLASS
SUMMARY: NESTED | FIELD | CONSTR | METHOD
DETAIL: FIELD | CONSTR | METHOD

java.util
Interface Iterator<E>

All Known Subinterfaces:
[ListIterator<E>](#)

All Known Implementing Classes:
[BeanContextSupport.BCSIterator](#), [Scanner](#)

public interface `Iterator<E>`

An iterator over a collection. Iterator takes the place of Enumeration in the Java collections framework. Iterators differ from enumerations in two ways:

- Iterators allow the caller to remove elements from the underlying collection during the iteration with well-defined semantics.
- Method names have been improved.

This interface is a member of the [Java Collections Framework](#).

Since:
1.2

See Also:
[Collection](#), [ListIterator](#), [Enumeration](#)

Method Summary

boolean	hasNext()	Returns true if the iteration has more elements.
E	next()	Returns the next element in the iteration.
void	remove()	Removes from the underlying collection the last element returned by the iterator (optional operation).

Method Detail

`hasNext`

```
ruler IteratorMonitor{
  ruleIDs { Start, Next }
  observes { hasNext, next }
  rules {
    always Start {
      hasNext(i), !Next(i) -> Next(i);
    }
    state Next(i) {
      next(i) -> Ok;
    }
    assert {Start, Next }
  }
  initials { Start }
}

monitor {
  uses { IM: IteratorMonitor }
  run IM .
}
```

```
public aspect iteratormonitor {
    RuleR ruler = new RuleR("src/examples/hasNext", false);

    void dispatch(String event, Object[] args) {...}

    pointcut scope() :
        !cflow(adviceexecution()) && if(true);

    pointcut hasNext(Iterator i) :
        call(* java.util.Iterator+.hasNext()) && target(i);

    pointcut next(Iterator i) :
        call(* java.util.Iterator+.next()) && target(i);

    before(Iterator i): hasNext(i) && scope() {
        dispatch("hasNext", new Object[]{i});
    }

    before(Iterator i): next(i) && scope() {
        dispatch("next", new Object[]{i});
    }
}
```

properties of Java library APIs

Enumeration (Java 2 Platform SE 5.0)

http://java.sun.com/j2se/1.5.0/docs/api/

Java™ 2 Platform Standard Ed. 5.0

Overview Package **Class** Use Tree Deprecated Index Help

PREV CLASS NEXT CLASS FRAMES NO FRAMES

SUMMARY: NESTED | FIELD | CONSTR | METHOD DETAIL: FIELD | CONSTR | METHOD

java.util

Interface Enumeration<E>

All Known Subinterfaces:
[NamingEnumeration<T>](#)

All Known Implementing Classes:
[StringTokenizer](#)

R₂: An enumeration should not be propagated after the underlying vector has been changed .

Method Summary

boolean	hasMoreElements()	Tests if this enumeration contains more elements.
E	nextElement()	Returns the next element of this enumeration if this enumeration object has at least one more element to provide.

```
ruler SafeEnum {
  ruleIDs {Start,Next, Update}
  observes {create_enum,call_next,update_source}

  rules {
    always Start {
      create_enum(v,e) -> Next(v,e);
    }

    state Next(v,e) {
      update_source(v) -> Update(e);
    }

    state Update(e) {
      call_next(e) -> Fail;
    }
  }

  initials { Start }
}
```

```
monitor {
  uses {S : SafeEnum}
  run S .
}
```

current limitations of RuleR

- still not as succinct as for example regular expressions in some cases (RE: 'next next').
- optimization not begun.
- it is a prototype under development, including language design.

end